

Measuring AFM wrong (and perhaps right)

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Scanning Probe Microscopy

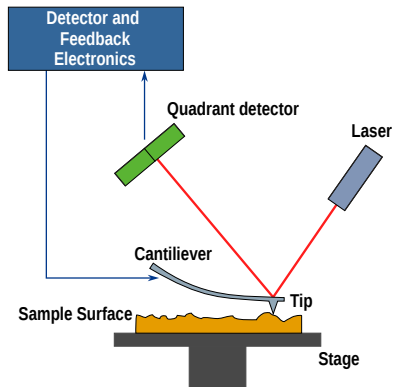
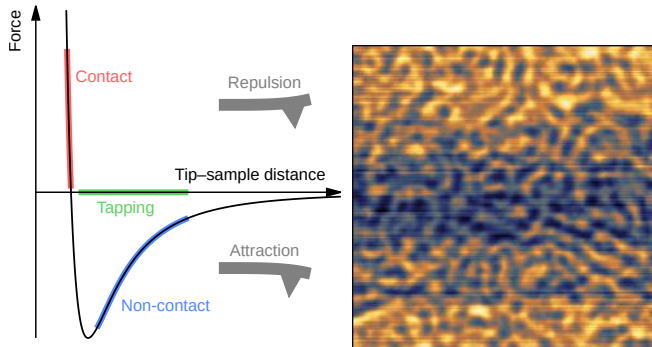


Image formation: Scanning the surface line by line



Anisotropy: Fast & slow axis

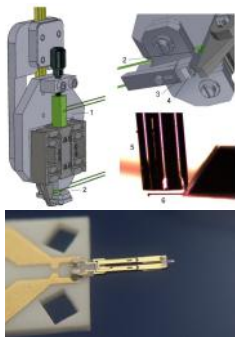
Open & closed loop

Techniques: Mechanical, electrical, magnetic, thermal, optical, ...

More in Petr Klapetek's lecture on Friday!

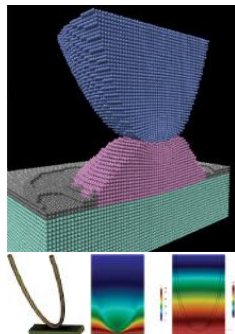
Quantitative SPM

Hardware



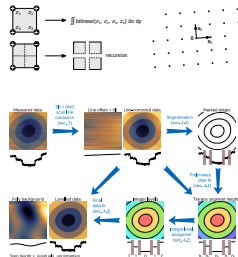
Stage & head
Probes
Electronics
Environmental
...

Physics



Probe-sample
interaction
Atomistic modelling
Molecular dynamics
FEM & FDTD
...

Algorithms



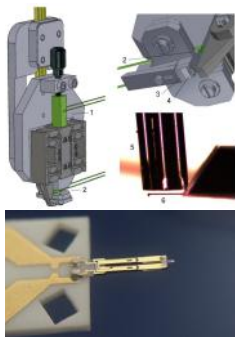
$$\hat{G}(\tau) = \frac{1}{L - \tau} \int_0^{L-\tau} \hat{z}(x) \hat{z}(x + \tau) dx$$

$$\frac{1}{L - \tau} \int_0^{L-\tau} \left[z(x) - \sum_j a_j \varphi_j(x) \right] \left[z(x + \tau) - \sum_k a_k \varphi_k(x + \tau) \right] dx$$

Filtering &
preprocessing
Feature recognition
Model fitting
Statistical
...

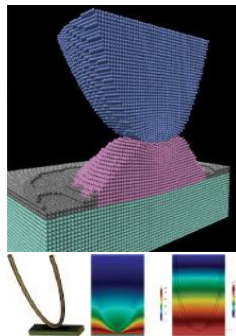
Quantitative SPM

Hardware



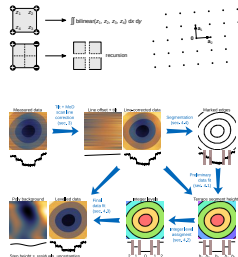
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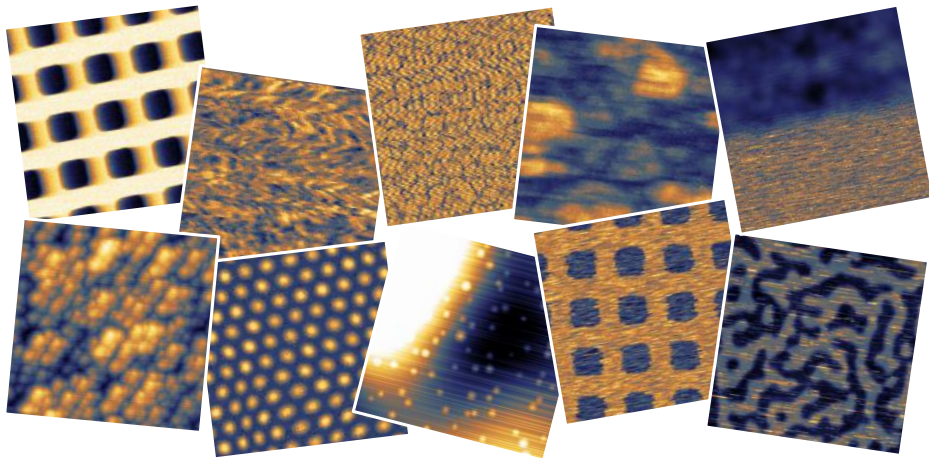
Filtering &
preprocessing
Feature recognition
Model fitting
Statistical
...

Secret ingredient



This talk?

Bad data? Easy!



Many effects conspire to sabotage our SPM measurements

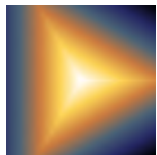
Mechanical & electromagnetic noise, laser interference, cross-talk, changes in probe properties & contact, contamination & tip convolution, bad feedback parameters, hysteresis & non-linearity, creep, aging, topography artefacts, ...

Good data?

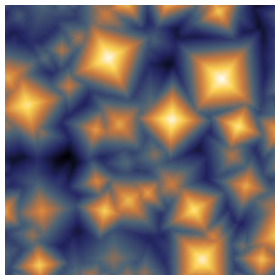
Tip convolution → convolution artefacts

Blind estimation

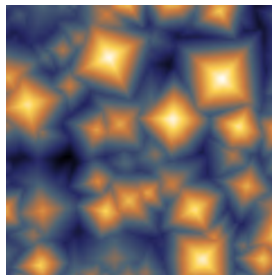
of tip shape using tip imaging
by sharp surface features



True tip shape



True surface



Measured (tip convolution)



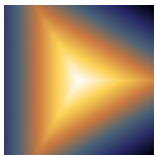
Reconstruction
(blind estimate)

Good data?

Tip convolution → convolution artefacts

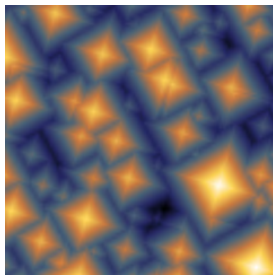
Blind estimation

of tip shape using tip imaging
by sharp surface features

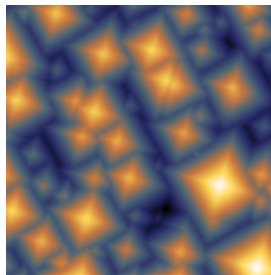


True tip shape

+



True surface



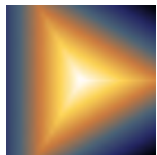
Measured (tip convolution)

Good data?

Tip convolution → convolution artefacts

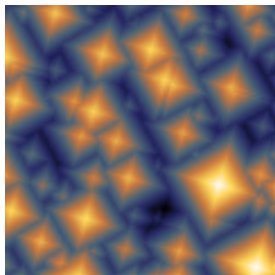
Blind estimation

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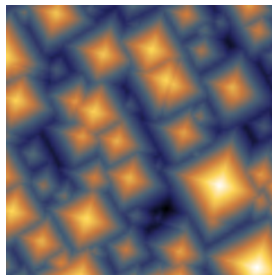
True tip shape

+



True surface

→



Measured (tip convolution)

→



Reconstruction
(blind estimate)



Similar: tip transfer/point spread function, etc.

Periodic structures



Different origins:

- ▶ lithography & laser interference
- ▶ atomic lattices
- ▶ self-organised wrinkles, domains, ...

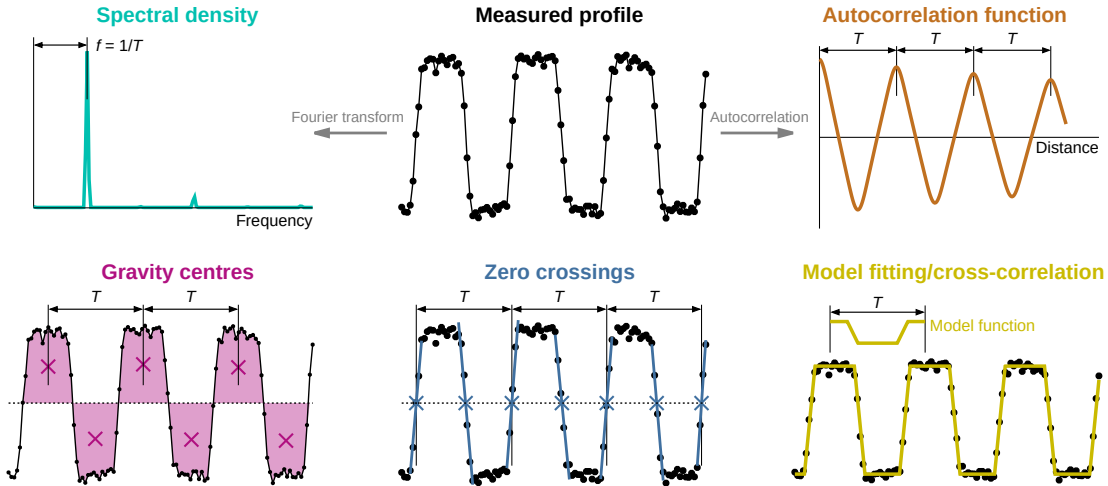
Data evaluation generally similar.

Different purposes:

- ▶ studying a structure/process
- ▶ instrument calibration
- ▶ *ex post* data correction

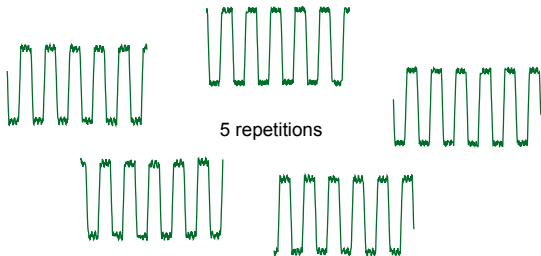
Pitch & height standards – but maybe not both from one measurement.

Evaluation of period/pitch



- Feature identification (direct space)
- Fourier transform
- Autocorrelation – not widely used

More is better



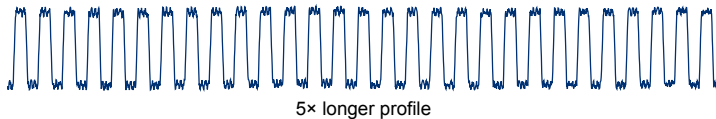
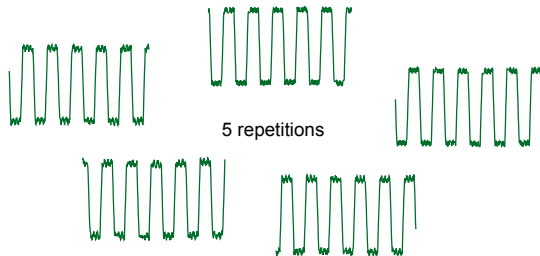
Warm up question

Measuring 5× is about:

- (a) $\sqrt{5\times}$ worse,
- (b) the same,
- (c) $\sqrt{5\times}$ better,
- (d) $5\times$ better,
- (e) $\infty\times$ better

than measuring once.

More is better



Warm up question

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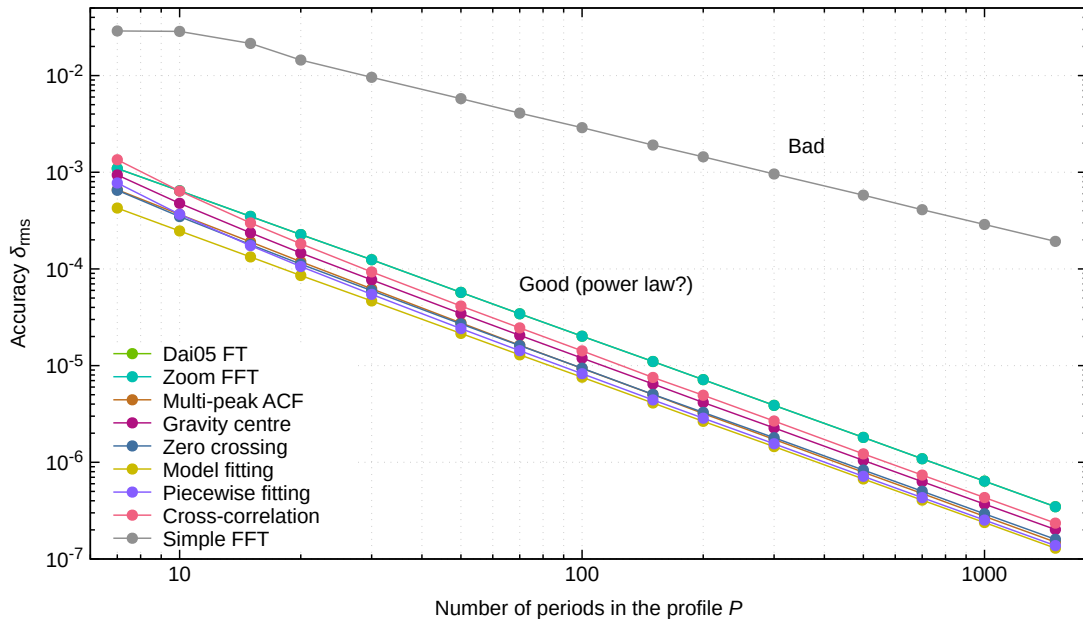
than measuring once.

One longer profile is:

- (a) 5× worse,
- (b) $\sqrt{5\times}$ worse,
- (c) the same,
- (d) $\sqrt{5\times}$ better,
- (e) 5× better.

than measuring 5 shorter ones.

Scaling



Scaling power

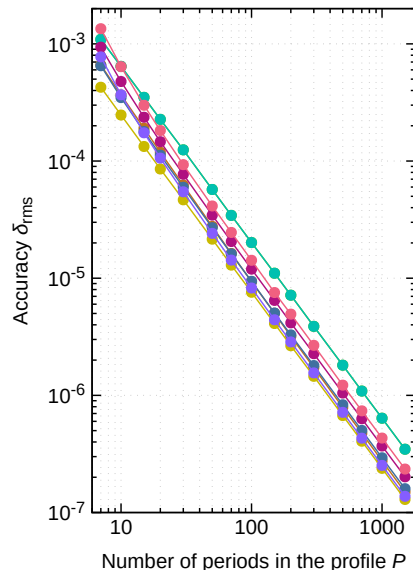
Model $x_n = nT$

$$\text{Estimate } \hat{T} = \sum_{n=1}^P nx_n / \sum_{n=1}^P n^2$$

$$\text{Dispersion } \Delta_T^2 = \sum_{n=1}^P \left(\frac{\partial \hat{T}}{\partial x_n} \right)^2 \Delta_x^2 = \Delta_x^2 / \sum_{n=1}^P n^2 \approx \frac{3}{P^3} \Delta_x^2$$

$$\text{Scaling } \Delta_T \approx \frac{1}{P^{3/2}} \sqrt{3} \Delta_x$$

- T – period (fitted)
- Δ_T – standard deviation of T
- Δ_x – location error in x
- P – number of periods



Scaling power

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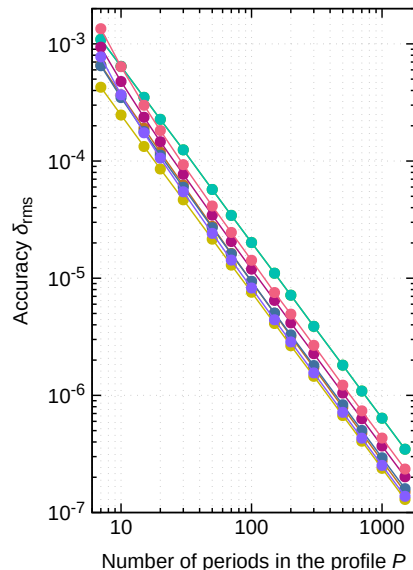
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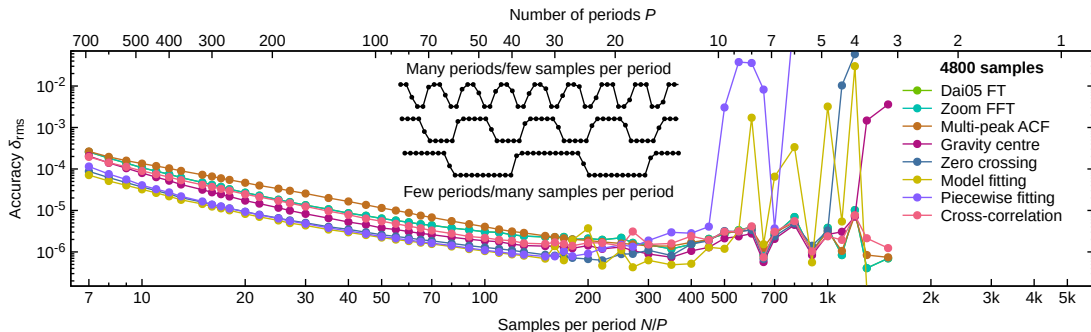
Scaling powers

- ▶ **Single long profile: $-3/2$**
- ▶ **Repeated measurement: $-1/2$**

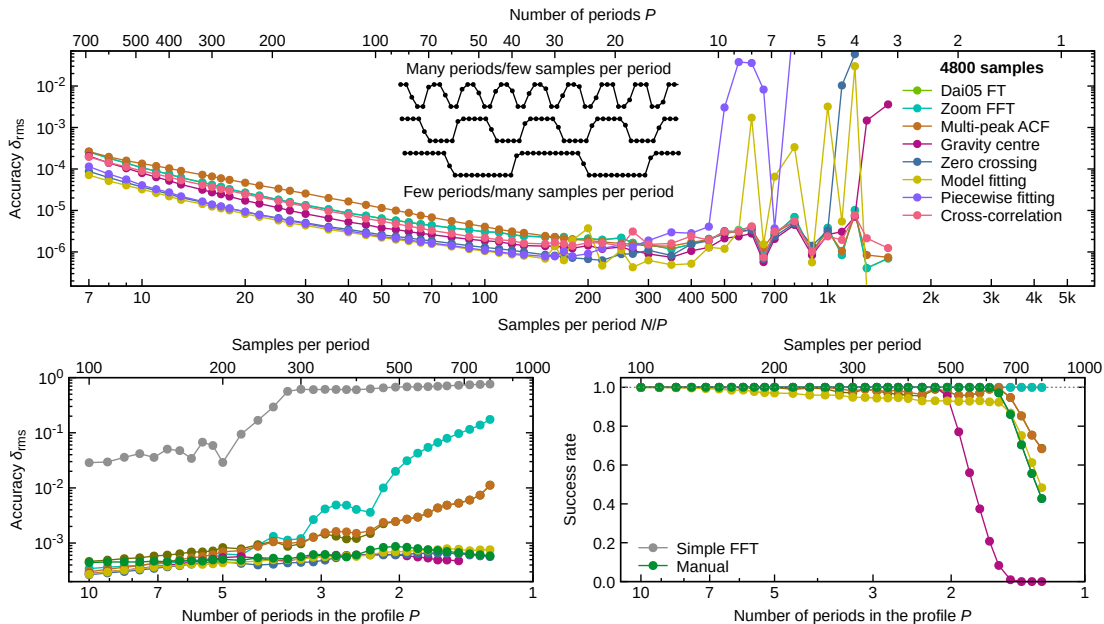
All good methods are similar – probably a theoretical limit



The extremes



The extremes



Steps on silicon

Secondary realisation of metre

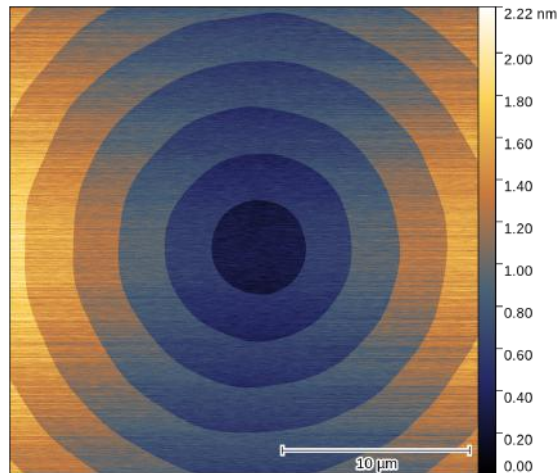
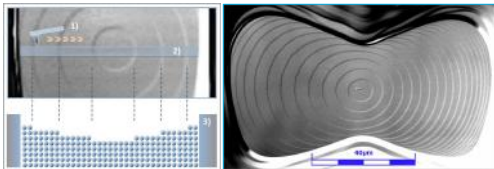
Preparation of the 2018 update of the SI
Silicon lattice spacing

$$d_{220} = 192.015\,571\,6(32) \times 10^{-12} \text{ m}$$

Practical SPM standard

Mono atomic steps on Si (111) surface
Prepared using molecular beam epitaxy

$$d_{111} = 313.560\,115\,1(53) \times 10^{-12} \text{ m}$$



Evaluation

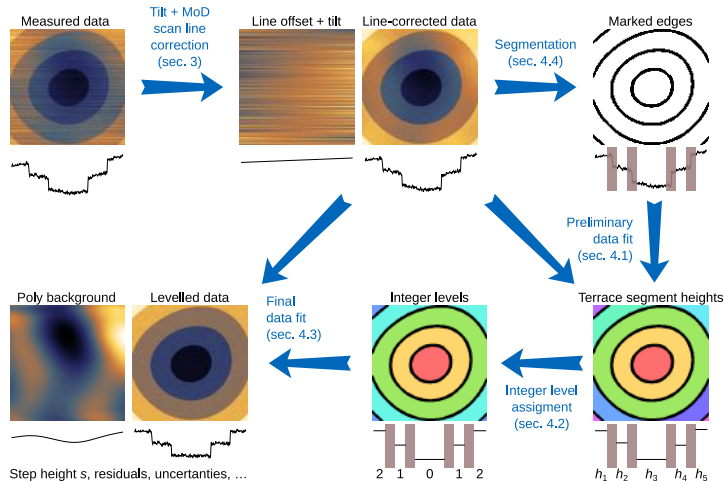
Preprocessing

- ▶ line correction
- ▶ edge detection
- ▶ terrace marking
- ▶ connectivity graph

Fitting

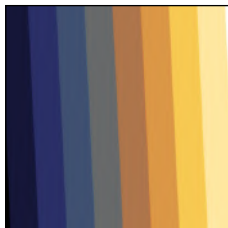
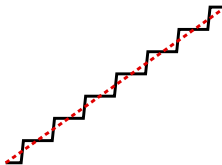
$$\text{Height}(x) = s \cdot \text{Level}(x) + \text{Poly}(x)$$

- s — step height (fitted)
 Level — levels (known integers)
 Poly — a polynomial (fitted)

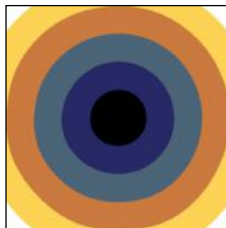
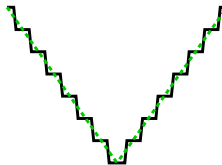


Overall shape

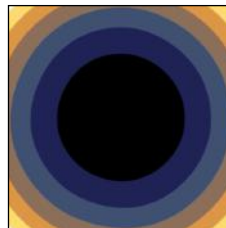
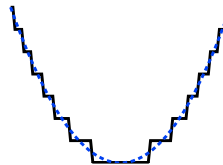
Staircase
 $x/2$



Amphitheatre
 $|x|$

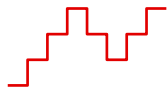


Parabolic
 x^2

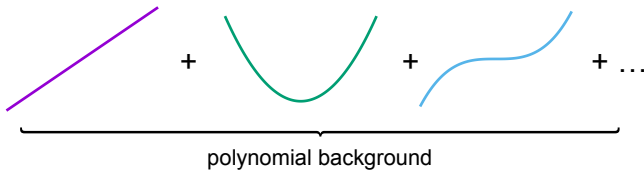


Which overall shape is the best? worst?

Fitting the profile



+



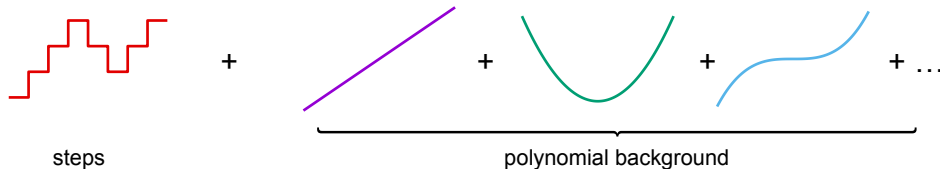
steps

$$\text{Height}(x) = s \cdot \text{Level}(x) + \text{Poly}(x)$$

Distinct fitting functions – **Good**

Indistinguishable functions – **Bad**

Fitting the profile



$$\text{Height}(x) = s \cdot \text{Level}(x) + \text{Poly}(x)$$

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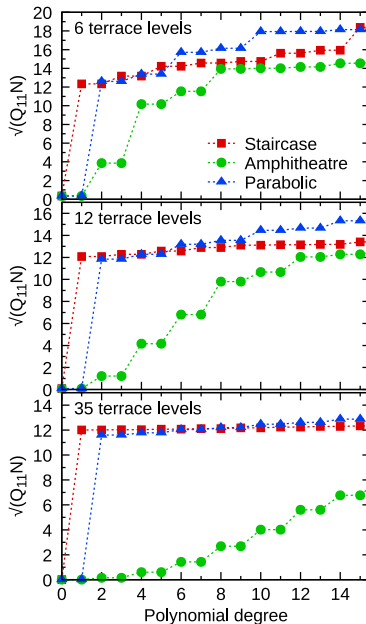
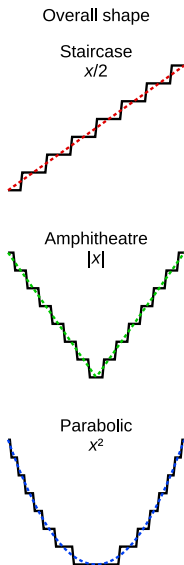
Staircase	– looks like x	– bad
Parabolic	– looks like x^2	– a bit less bad
Amphitheatre	– does not look like any polynomial	– good

$$\text{Step error } \Delta_s \propto \sqrt{Q_{11}} \cdot \text{Noise}$$

$$\text{Cofactor matrix } \mathbf{Q} = (\text{Normal matrix})^{-1}$$

- ▶ does not depend on noise
- ▶ computed from scalar products of basis fitting functions

The matrix



Assumptions

- ▶ ideal geometry
- ▶ no around-step exclusion
- ▶ amount of data $N \rightarrow \infty$

$\sqrt{Q_{11}N}$ plotted instead of $\sqrt{Q_{11}}$
for meaningful $N \rightarrow \infty$ limit

Few terraces

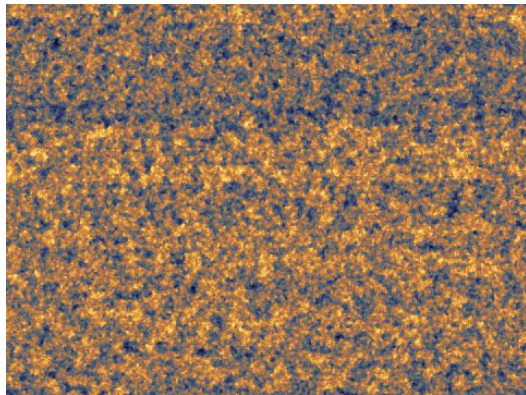
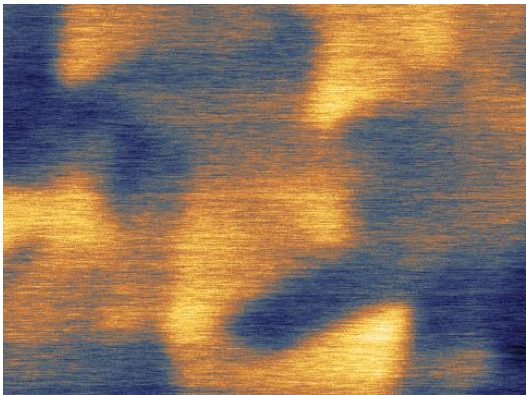
- ▶ poor measurement
- ▶ small difference

Many terraces

- ▶ good measurement
- ▶ huge difference

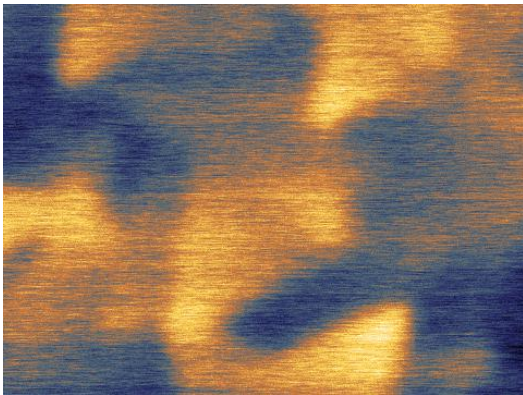


Which one is it?

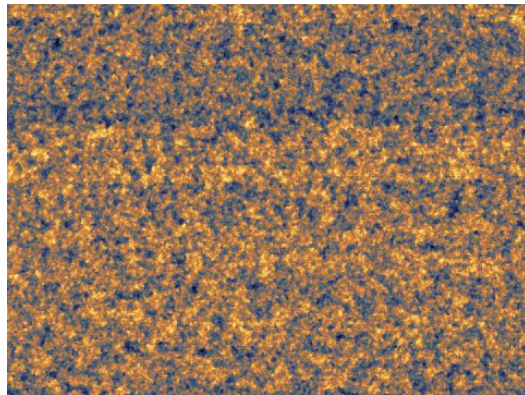


Which one is better for roughness? Left? Right? Neither?

Which one is it?



Pretty bad, $\gtrsim 30\%$ bias & poor representativeness.



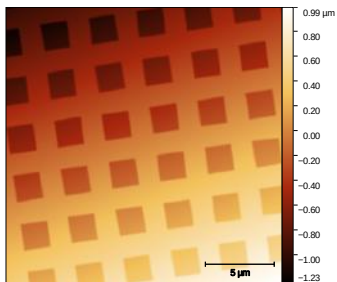
Probably good for evaluation.

Scan line must be long to avoid losing the lower spatial frequencies.

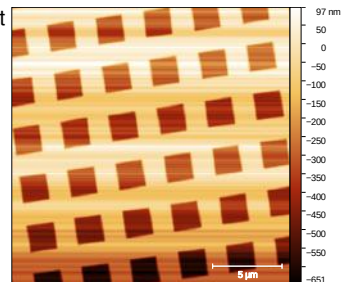
Governed by $\alpha = T/L$. Should be $\alpha \ll 1$.

In AFM usually incompatible with 'can nicely see features'.

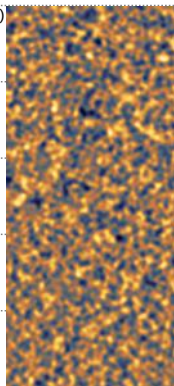
Sample tilt



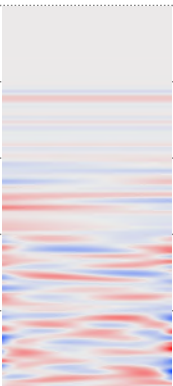
Scan line misalignment



Not levelled (a)



(b)

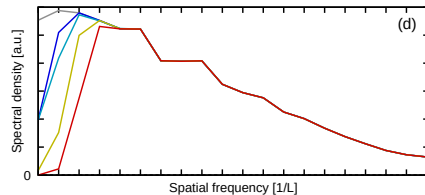
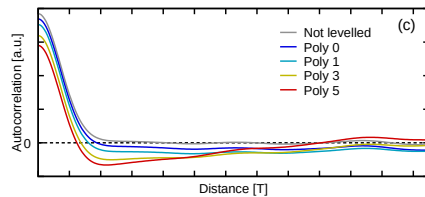


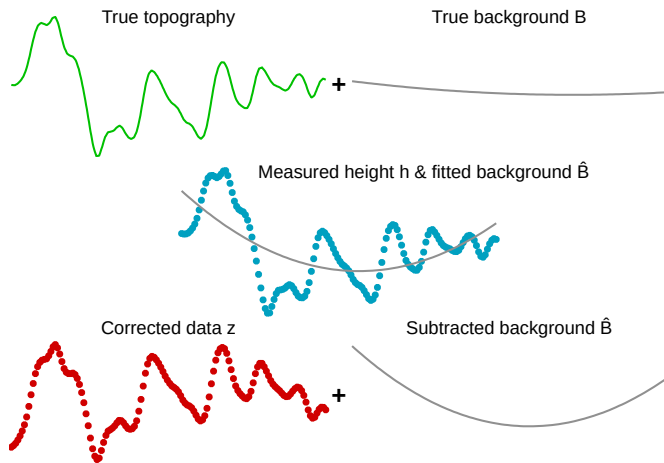
Poly 0

Poly 1

Poly 3

Poly 5

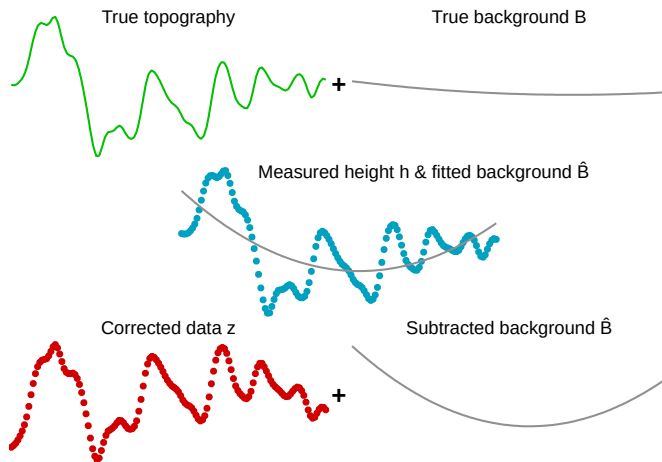




Bias of mean square roughness σ

$$E[\hat{\sigma}^2] = \sigma^2 - 2^D \int_0^1 C_n(t) G(tL) dt$$

- T – autocorrelation length
- D – dimension (1, 2, ...)
- G – autocorrelation function
- C_n – ugly function
- n – polynomial degree



Bias of mean square roughness σ

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D – dimension (1, 2, ...)

G – autocorrelation function

C_n – ugly function

n – polynomial degree

Autocorrelation function to rescue

$$E[\hat{G}] = G - R_n G$$

G – autocorrelation function

R_n – even uglier linear operator

G knows about its own bias!

Fit $G - R_n G$ instead of G to experimental data

$$G_{\text{Gauss}}^{\text{bias}}(\tau) \approx \sigma^2 \exp\left(-\frac{\tau^2}{T^2}\right) - \sqrt{\pi} n \sigma^2 \frac{T}{L} \left(1 + \frac{\tau}{L}\right) + n^2 \sigma^2 \frac{T^2}{L^2} \left(1 + \frac{2\tau}{L}\right)$$

Or invert $G = (1 - R)^{-1} \hat{G}$ (adventurous)

Conclusions

- ▶ Measuring wrong is easy.
- ▶ Solid 'hardware' part \nrightarrow useful data.
- ▶ *What* do you measure?
- ▶ Intuition often fails us.
- ▶ Simulate!

Almost everything is implemented in Gwyddion.



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Almost everything is implemented in Gwyddion.

Nothing you saw was real SPM data.

